

HPWM3 Isolated Square Wave Amplifier

1 Features

- Input voltage: $\pm 20V \pm 0.2V$
- Continuous output current 5A
- Signal supply: $\pm 15V \pm 0.15V$
- Input DC level: $-10V \sim +10V$
- Include two separate power amplifier circuits
- Unique ternary output characteristics
- With current negative feedback, the output has constant current source characteristics



45 × 40 × 6.5mm³

Weight: 65g

2 Applications

DC motor drive control

Drive the reactive load

3 Description

HPWM3 Isolated Square Wave Amplifier is composed by two completely independent of the pulse amplifier power amplifiers. According to the size of the input control voltage change, the single-way amplifier will output three consecutive amplitudes of the square wave to the motor load, and the circuit has a current negative feedback characteristic, can reduce the motor load loss and improve the anti-jamming capability.

This series of products are made of thick film hybrid integrated process, metal sealed package. Product design and manufacturing meet the requirements of MIL-STD and detailed specifications, the quality level is H-class.

4 Technical Specifications

Form 1: Rated conditions and Operating conditions

Absolute maximum rating	Recommended operating conditions
Positive +Vcc: +16.5V Negative -Vcc: -16.5V Positive +Vs: 25V Negative -Vs: -25V Input voltage Vin: $\pm 12V$ Storage temperature Tstg: $-55^{\circ}C \sim 125^{\circ}C$ Lead welding temperature (10s) Th: $300^{\circ}C$ Junction Temperature Tj: $150^{\circ}C$	Positive +Vcc: $15V \pm 0.15V$ Negative -Vcc: $-15V \pm 0.15V$ Positive +Vs: $20V \pm 0.2V$ Negative -Vs: $-20V \pm 0.2V$ Input voltage Vin: $\pm (0V \sim 10V)$ Operating Temperature (Case) Tc: $-55^{\circ}C \sim 125^{\circ}C$

Form 2 Electrical characteristics

Load	Character	+Vcc= $15V \pm 0.15V$ -Vcc= $-15V \pm 0.15V$ +Vs= $20V \pm 0.2V$ -Vs= $-20V \pm 0.2V$ $-55^{\circ}C \leq Tc \leq 125^{\circ}C$	HPWM3		Unit	
			Min	Max		
1	Continuous output current	Full load, VI=1.5	1	-	A	
	Output voltage	Full load	VI=-10V	19	21	V
			VI=+10V	-19	-21	
	Output frequency	-	11	13	KHZ	
	Linearity	-	95			
Symmetry	-	95				
2	Continuous output current	Full load, VI=1.5	1	-	A	
	Output voltage		VI=-10V	19	21	V
			VI=+10V	-19	-21	
	Output frequency		11	13	KHZ	
	Linearity		95			
Symmetry		95				

5 Lead function descriptions

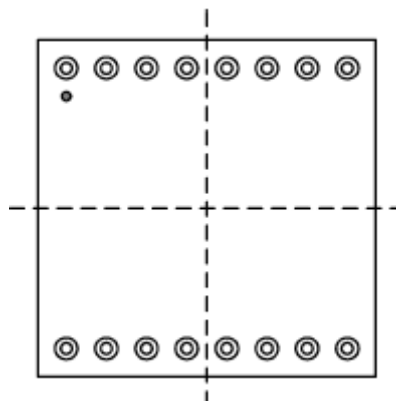


Fig 2 upward view

Form 3 Pin Designation

No	symbol	Designation	No	symbol	Designation
1	F1	1 st output square wave	9	GNDS	Signal ground
2	V _{I1}	1 st input	10	NC	NC
3	FF1	1 st negative feedback	11	OUT ₂	2 nd output
4	-V _{cc}	Power supply -15V	12	GNDP	Power ground
5	+V _{cc}	Power supply +15V	13	-V _s	Power supply -20V
6	F2	2 nd output square wave	14	NC	NC
7	V _{I2}	2 nd input	15	OUT ₁	1 st output
8	FF2	2 nd negative feedback	16	+V _s	Power supply +20V

6 Circuit principle frame diagram

The ternary pulse-width power amplifier includes a signal processing circuit, a half-bridge drive circuit and a power amplifier.

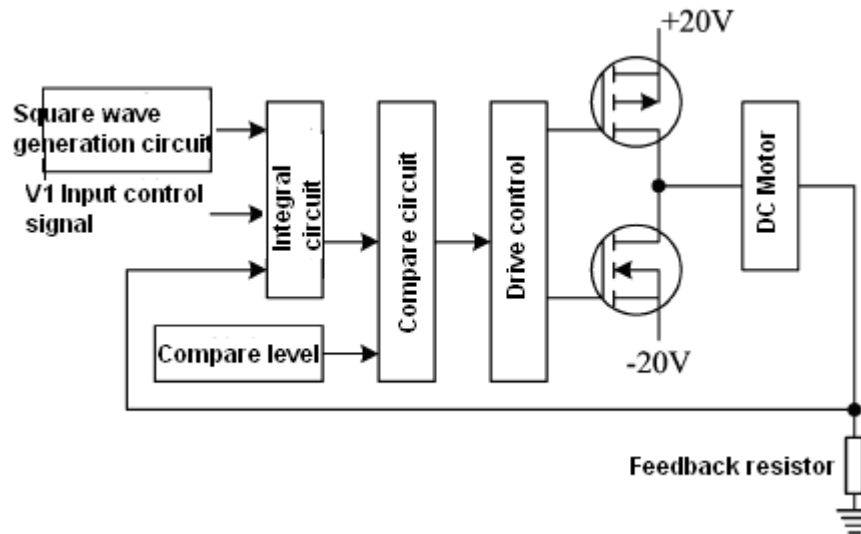
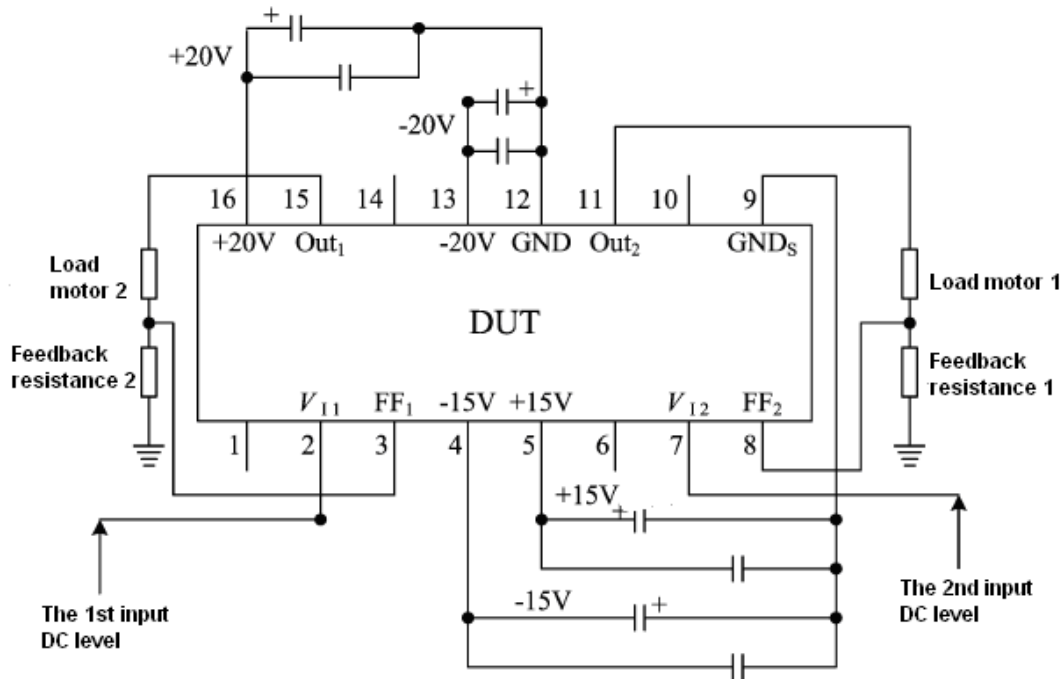


Fig 3 signal processing circuit

A triangle wave signal is generated by input control signal and square wave generator circuit, the effect of triangle wave signal and fixed level can generate width modulated square wave signal. Drive circuit can make isolation and distribution for the front width modulated square wave signal, then drive the power tubes, to make power amplifier and drive load for DC motor..

7. Typical Connection Diagram

HPWM3 Isolated Square Wave Amplifier is composed by two completely independent of the pulse amplifier power amplifiers



7.1 Ternary output

The difference between Ternary PWMA and the general PWMA is that the amplifier output of the three states, namely, ternary characteristics, as shown below. Figure 4 shows the input control voltage is 0, the output is positive and negative symmetrical narrow pulse, the average DC is 0, and two output signals are reverse; When the input voltage reaches half of the input voltage, the negative pulse disappears and becomes a positive unipolar type wide square wave, and the negative pulse duty is reduced. When the input voltage reaches -0.1V, As shown in Figure 5; Input control voltage is increased in positive direction, the output negative pulse duty cycle increases, positive pulse duty cycle decreases, when the input voltage reaches +0.1V or so, the positive pulse disappears and becomes negative type wide square wave, as shown in Figure 6.

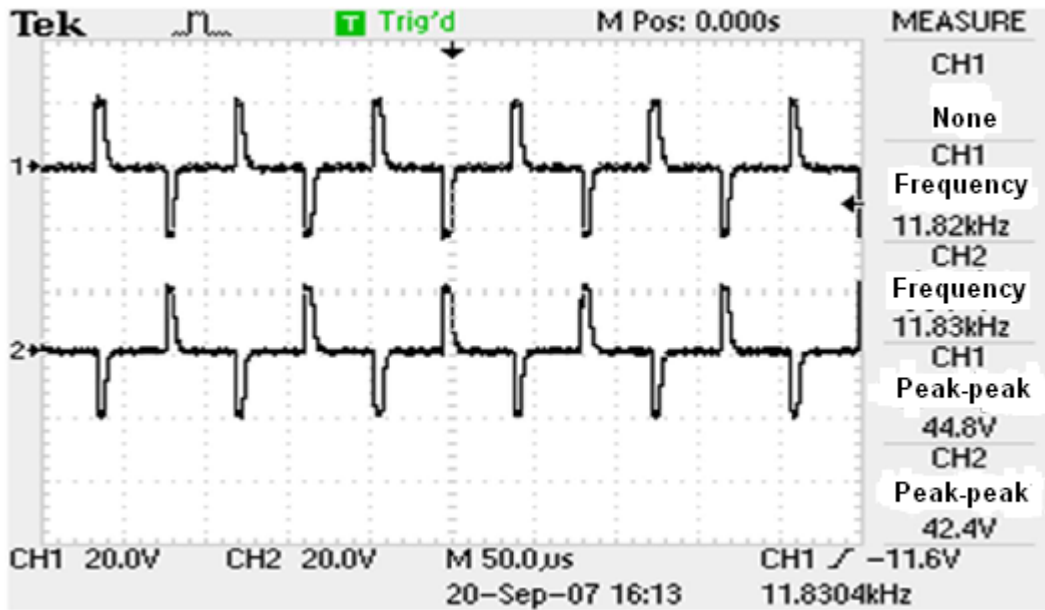


Fig 4 The amplifier output two waveforms when the input control voltage is 0.

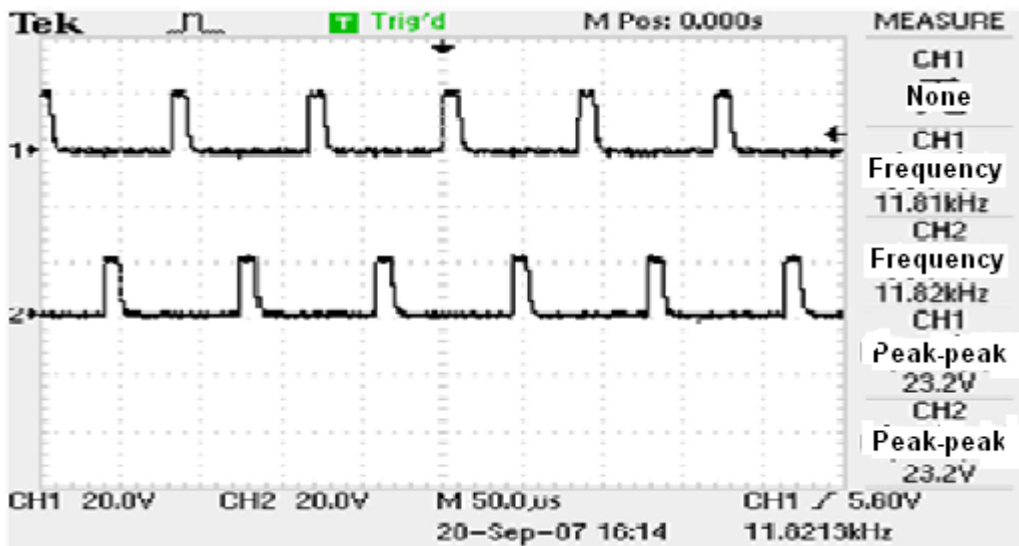


Fig 5 The amplifier output two waveforms a point waveforms when input control voltage is negative. ($V < -0.1V$)

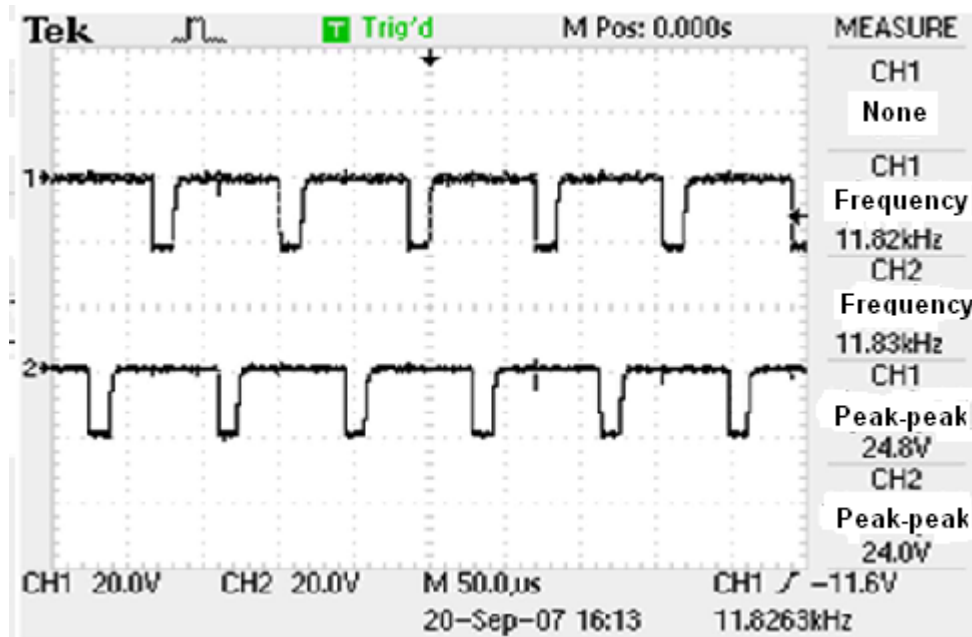


Fig 6 The amplifier output two waveforms a point waveforms when input control voltage is positive.($V > 0.1V$)

7.2 Power supply bypass

Power supply should have sufficient bypass capacitors to ensure proper operation, otherwise it may be unstable and reduce efficiency, and the output may be oscillated. $\pm 20V$ power supply should connect an at least $1\mu F$ ceramic capacitor paralleled with a low value ESR capacitor, the capacitance should be at least $10\mu F/A$; for $\pm 15V$ power supply also requires a $0.1\mu F \sim 0.47\mu F$ ceramic capacitor paralleled with a low ESR value of $6.8\mu F \sim 10\mu F$ bypass capacitor, All bypass capacitors should be connected as close as possible to the corresponding power supply root.

7.3 Output constant current characteristics:

Figure 7 circuit, assuming that the input DC control voltage signal is V_i , the output DC current is I_o , then the circuit gain $A = I_o/V_i$, because it is a series of negative feedback, F1 is the symmetrical positive and negative square wave when average DC voltage is 0, then $V_i/R_1 \approx U_f/R_3 \approx R_f/R_3$, launched $I_o/V_i = R_3/R_1R_f$, the circuit gain $A = I_o/V_i = R_3/R_1R_f$, the formula shows that the circuit gain is basically independent of the carrier gain A_{od} and the load DC motor R_1 and other parameters, that is, when the input DC level is stable and the DC motor changes, the output square wave duty cycle will change, thus ensuring the output DC I_o which improves the ability to adapt to the motor load, so that the output has a constant current source characteristics.

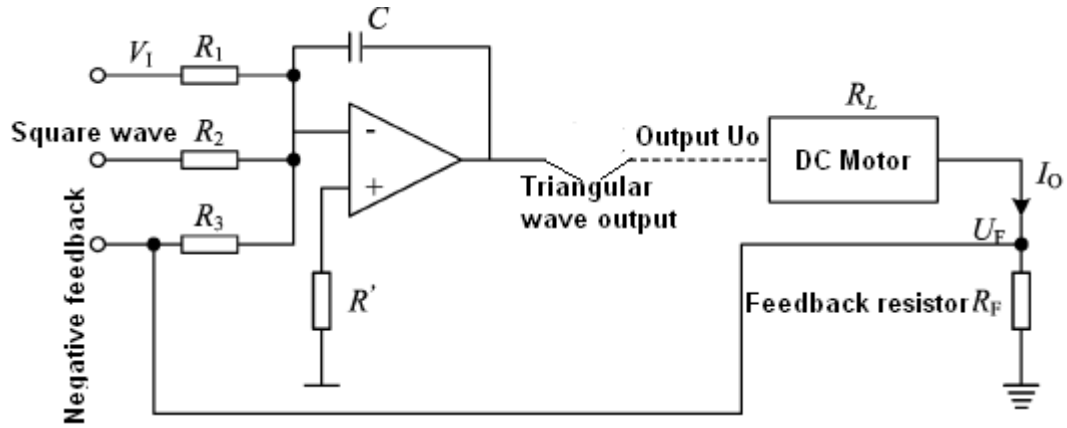


Fig 7 Current series negative feedback circuit

8. Package Specifications

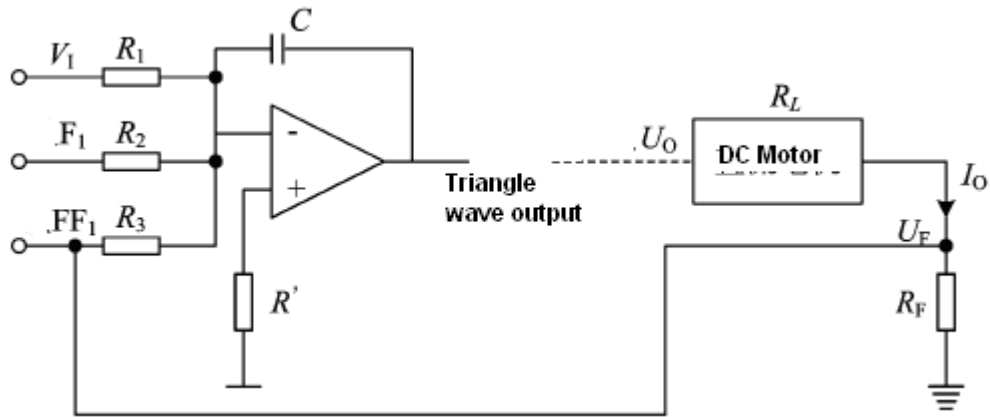


Fig 5

Application notes please refer to the appendix, must read it carefully